MITSUBISHI Analog input/ output module

User's Manual (Hardware)

A1S63ADA

Thank you for buying the Mitsubishi general-purpose programmable logic controller MELSEC-A Series

Prior to use, please read both this manual and detailed manual thoroughly and familiarize yourself with the product.



MODEL	A1S63ADA-U-(H/W)
MODEL	12 10 42
CODE	133643

IB(NA)-68474-H(1112)MEE

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• SAFETY PRECAUTIONS • (Read these precautions before using this product.)

Before using this product, please read this manual and the relevant manuals carefully and pay full attention to safety to handle the product correctly. These precautions apply only to this equipment. Refer to the CPU module user's manual for a description of the PC system safety precautions.

In this manual, the safety precautions are classified into two levels:

" WARNING" and " CAUTION".

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.
Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Under some circumstances, failure to observe the precautions given under

"<u>/</u>CAUTION" may lead to serious consequences.

Observe the precautions of both levels because they are important for personal and system safety.

Make sure that the end users read this manual and then keep the manual in a safe place for future reference.

[DESIGN PRECAUTIONS]

• Configure a safety circuit on the outside of the PC so that the entire system works to a safe side even when the external power failure occurs or PC main unit fails.

An erroneous output or operation may result in an accident.

• Use the PC in the environment given in the general specifications section of the applicable CPU module user's manual.

Failure to do so may result in electric shock, fire, or erroneous operation or may damage or degrade the equipment.

• Do not bundle, or install, the control cables with, or near, the main circuit and power cables.

Keep them at least 100 mm (3.9 inch) away from such cables. Noise may cause erroneous operation.

 At power ON/OFF, voltage or current may instantaneously be output from the output terminal of this module. In such case, wait until the analog output becomes stable to start controlling the external device.

[INSTALLATION PRECAUTIONS]

- Insert the tabs at the bottom of the module into the holes in the base module before installing the module. Be sure to install the module in the base module with screws tightened to the specified torque. Improper installation may cause erroneous operation, accident, or the module to fall out.
- Do not directly touch the module's conductive parts or electronic components.

Doing so could cause malfunction or trouble in the module.

[WIRING PRECAUTIONS]

- If noise generates frequently, ground the AG and FG terminals using the PC dedicated class-D ground (class-three ground) or higher.
 Failure to do so may result in erroneous operation.
- Confirm the rated voltage and terminal arrangement of the module before wiring it to the PC.

If a power supply of different rating is connected or a wiring is performed erroneously, fire or accident may result.

- Tighten the terminal screws to the specified torque. Loose terminal screws may cause a short circuit or erroneous operation. If excessively tightened, the terminal screws may be damaged, and cause a short circuit or erroneous operation.
- Be sure that cuttings, wire chips, or other foreign matter do not enter the module.

Foreign matter may start a fire or cause an accident or erroneous operation.

[STARTING AND MAINTENANCE PRECAUTIONS]

- Do not touch live terminals. It may cause erroneous operation.
- Be sure to shut off all phases of the external power supply used by the system before cleaning or retightening the terminal screws. Not doing so can cause the module to fail or malfunction.
- Do not disassemble or rebuild the module. It may cause accidents, erroneous operation, injury, or fire.
- Be sure to shut off all phases of the external power supply used by the system before mounting or removing the module. Not doing so may cause damage to the module.
- Do not install/remove the terminal block more than 50 times after the first use of the product. (IEC 61131-2 compliant)
- Before handling the module, always touch grounded metal, etc. to discharge static electricity from the human body.
 Failure to do so may cause the module to fail or malfunction.

[OPERATING PRECAUTIONS]

 Do not output (ON) "Use Prohibited" signals from the PC CPU to the special module.

Doing so could erroneously operate the PC system.

[DISPOSAL PRECAUTIONS]

• When disposing of this equipment, handle it as industrial waste.



(1) Mitsubishi programmable controller ("the PRODUCT") shall be used in conditions;

i) where any problem, fault or failure occurring in the PRODUCT, if any, shall not lead to any major or serious accident; and

ii) where the backup and fail-safe function are systematically or automatically provided outside of the PRODUCT for the case of any problem, fault or failure occurring in the PRODUCT.

(2) The PRODUCT has been designed and manufactured for the purpose of being used in general industries. MITSUBISHI SHALL HAVE NO RESPONSIBILITY OR LIABILITY (INCLUDING, BUT NOT LIMITED TO ANY AND ALL RESPONSIBILITY OR LIABILITY BASED ON CONTRACT, WARRANTY, TORT, PRODUCT LIABILITY) FOR ANY INJURY OR DEATH TO PERSONS OR LOSS OR DAMAGE TO PROPERTY CAUSED BY the PRODUCT THAT ARE OPERATED OR USED IN APPLICATION NOT INTENDED OR EXCLUDED BY INSTRUCTIONS, PRECAUTIONS, OR WARNING CONTAINED IN MITSUBISHI'S USER, INSTRUCTION AND/OR SAFETY MANUALS, TECHNICAL BULLETINS AND GUIDELINES FOR the PRODUCT. ("Prohibited Application")

Prohibited Applications include, but not limited to, the use of the PRODUCT in;

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* The manual number is given on the bottom right of the front cover.

Print Date	* Manual Number	Revision
Oct.,1994	IB (NA)-68474-A	First edition
Feb.,1999	IB (NA)-68474-B	Addition
		Safety precautions
		Partial Correction
		Section 3.1
Dec.,1999	IB (NA)-68474-C	Partial Correction
		Chapter 2
Nov.,2001	IB (NA)-68474-D	Partial Correction
		Contact ad dress (Back cover)
Oct.,2002	IB (NA)-68474-E	Partial Correction
		Chapter 2, Section 5.2
Sep.,2005	IB (NA)-68474-F	Addition
		Conformation to the EMC Directive and
		Low Voltage Instruction
		Partial Correction
	-	SAFETY PRECAUTIONS
Sep.,2006	IB (NA)-68474-G	Partial Correction
		SAFETY PRECAUTIONS
Dec.,2011	IB (NA)-68474-H	Addition
		SAFETY PRECAUTIONS (Chinese),
		CONDITIONS OF USE FOR THE
		PRODUCI

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About the Manuals

The following manuals are related to this product. Order them if necessary.

Detailed manuals

Manual Name	Manual No. (Model code)
Analog input/output module type A1S63ADA	IB-66435
User's Manual.	(13JE30)

COMPLIANCE WITH EMC AND LOW VOLTAGE DIRECTIVES

(1) Method of ensuring compliance

To ensure that Mitsubishi programmable controllers maintain EMC and Low Voltage Directives when incorporated into other machinery or equipment, certain measures may be necessary. Please refer to one of the following manuals.

• User's manual for the CPU module used

• User's manual (hardware) for the CPU module or base unit used The CE mark on the side of the programmable controller indicates compliance with EMC and Low Voltage Directives.

(2) Additional measures

No additional measures are necessary for the compliance of this product with EMC and Low Voltage Directives.

1. OVERVIEW

This manual describes specifications, handling and wiring of an A1S63ADA Analog input/output module (hereinafter referred to as the A1S63ADA).

2 PREFORMANCE SPECIFICATIONS

The performance specifications of the A1S63ADA are shown below.

Item			Specifications								
	A	·	Voltage:-10 to 0 to 10VDC(input resistance: $1M\Omega$)								
	Analog	i input	Current:-20 to 0 to 20mADC(input resistance: 250Ω)								
			-4096 to	4095 (w	hen res	olu	ution is se	et to 1/40	000)	/	
	Digital output		-8192 to	-8192 to 8191 (when resolution is set to 1/8000)							
			-12288 t	0 12287	(wnen r	es	olution is		/12000)	.4	
			Anal	og input		1	/4000	Digitai			12000
	1/0		10\/			1 100	<u>74000</u> 10	80	00	120	00
5	charac	teristics	5\/ or 20	mΔ		+0(20(00	40	00	60	00
rsic	*1		0V or 4n	nΔ	2	200	0	-0	0	00	0
Š	•		-5V or -2	20mA	-2	200	no	-40	00	-60	00
Ŋ			-10V	2011/2 (-00 40(00	-80	00	-120	00
			Voltage		2.5	m\	/	1.25	mV	0.83m	NV
-A	Max. re	esolution	Current		10µ	ιA	•	5μA		3.33µ	A
	Conve	rsion			1m:	s/c	ch	2ms/	′ch	3ms/c	h
	speed	-1									
	accura	ai cy*2	±1%		±4	0		± 80		± 120	I
	Absolute max.		Voltage:	Voltage: \pm 15V Current: \pm 30mA*3							
	Analog points	j input	2 channe	channel							
				Voltage output					Curre	ent output	
			-4000 to 4000				0 to 400	00			
			(when re	(when resolution is set to 1/4000)				(when r 0 to 800	esolutio	n is set to	1/4000)
	Digital	input	(when re	(when resolution is set to 1/8000)				(when resolution is set to 1/8000)			
			-12000 t	12000 to 12000			,	Ò to 12000			
			(when re	when resolution is set to 1/12000)				(when resolution is set to 1/12000)			
uo	Analaa		-10 to 0	to 10VD	C(exterr	nal	load	0 to 20mADC(external load			
<u>ersi</u>	Analog	συιραι	resistanc	ce:2k Ω t	o 1MΩ)			resistance:0 Ω to 600 Ω)			
-A conve	1/0	10		1/8000	1/12000	א ס כ י	Analog output value	1/4000	1/8000	1/12000	Analog output value
Ġ	charac	teristics	4000	8000	12000		10V	4000	8000	12000	20mA
	*4		2000	4000	6000		5V	2000	4000	6000	12mA
	•		0	0	0		0V	0	0	0	4mA
			-2000 -4000	-4000 -8000	-6000 -12000		-5V -10V				
	Max.	1/4000	2.5mV					5μΑ	1	1	1
	reso-	1/8000	1.25mV					2.5µA			
	lution	1/12000	0.83mV					1.7μA			

Item			Specifications						
		Voltage output Current outpu							
	Conversion speed*5	1	ms(1/4000) 2	2ms(1/8000) 3	ms(1/12000)			
	General accuracy*6	\pm 1%(\pm 0.1V)			± 1%(±	\pm 1%(\pm 0.2mA)			
conversion	Solute max. output	\	Voltage: \pm 12V Current: + 28mA						
	Output shorting protection	F	Provided						
	Analog output points			1channel					
Common to A-D and D-A			Specific isolated area	Isolation method	Dielectric withstand voltage	Insulation resistance			
conversions	Isolation specifications		Between I/O terminal and PLC power supply	Photocoupler isolation	500V AC for 1 minute	$5M_{\Omega}$ or more (measured with a 500V DC insulation resistance tester)			
			Between channels	Not isolated	-	-			
Conversion s loop control*	speed in simple 7	4ms(1/4000) 7ms(1/8000) 9ms(1/12000)							
Number of occupying I/O		32 points							
Connection terminal block		20-point terminal block (M3.5 × 7 screw)							
Applicable w	ire size	С	$0.75 \text{ to} 1.5 \text{mm}^2$						
Applicable crimp terminal		1.25-3.5 1.25-YS3A 2-3.5 2-YS3A V1.25-M3 V1.25-YS3A V2-3.5 V2-YS3A							
Internal curre (5 VDC)	ent consumption	С).8A						
Weight		0.3kg							

The offset and gain are set as shown below as the default setting.

CH1 ... Offset: 0V/4mA, Gain: 5V/20mA

CH2 ... Offset: 0V/4mA, Gain: 5V/20mA

CH3 ... Offset: 0V/4mA, Gain: 10V/20mA

*1: For offset value: 0V/4mA, gain value: 5V/20mA

- *2: This is the accuracy in respect to the maximum digital output value. The maximum digital output value is the maximum value at the selected resolution, and is the same for either a current input or voltage input.
- *3: Current value indicates value of instant input current that does not break module inner electrical resistance.
- *4: For offset value: 0V/4mA, gain value: 10V/20mA
- *5: Depending on the timing of reading the digital value from the PLC CPU, the process may be carried out with a delay of up to one conversion processing time. The response time for the amplifier to output the D/A converted data to an external source is "maximum 1ms".
- *6: This is the accuracy in respect to the maximum analog output value.
- *7: The response time for the amplifier to output the D/A converted data to an external source is "1ms". For the general specifications, refer to the User's Manual for the PLC CPU in use.

POINT

For approx. 30 minutes after the power is turned ON, the A/D conversion value will fluctuate due to the effect of the self-generated heat.

If this fluctuation is a problem, start control after warming up for approx. 30 minutes. In the same manner, wait approx. 30 minutes to warm up before adjusting the offset/gain value (user-set).

3.1 Names of each part

The names of each part are explained in this section.



No.	Name		Details						
	RUN LED	This indica	This indicates the A1S63ADA operation state.						
		 Normal m 	ode						
		LED ON:	In normal operation						
		Flickering	: Setting data error						
		LED OFF	: 5V power OFF or watch o	log timer error					
		 Test mod 	e						
		Flickering	: The LED flickers at a 0.2	5 second					
(1)			interval when the offset/g	jain select					
			switch is set to "OFFSET	⁻ " or "GAIN". If					
			the CH3 setting value is	set above the					
			setting range with the UF	P/DOWN switch,					
			the LED will flicker at a fast 0.1 second						
			interval.						
		LED OFF	: The offset/gain select sw	ritch is set to					
			"SET".						
	Channel, resolution	This sets the	e channel for adjusting th	e offset/gain					
	select switch	value and the resolution.							
		• Normal m	Normal mode: Invalid						
	СН —	(Eastly astting: 0)							
		Catting		lly setting. 0)					
		Setting	Olisel/gain	Resolution					
		value							
	9			1/1/000					
(2)				1/14000					
		3	CH3						
		4	CH4	4/0000					
		5	CH5	1/8000					
		6	CH6						
		7	CH7						
		8	CH8	1/12000					
		9	CH9						
	Offset/gain select	OFFSET p	osition: The offset value is	adjusted.					
	switch	SET pos	ition : When moved from	OFFSET to SET,					
(3)			the offset value is r	egistered.					
(0)	SET		When moned from	GAIN to SET,					
	GAIN	the gain value is registered.							
		GAIN po	sition: The gain value is a	adjusted.					

No.	Name	D	etails
	UP/DOWN switch	This increments or decre or gain value.	ements the CH3 offset value
(4)		Time at UP/DOWN position Less than 1.5s 1.5s or more	Increment/decrement width Voltage: approx. 2.5mV Current: approx. 5µA Voltage: approx. 50mV
			Current: approx. 5µA
(5)	Test mode terminal $ \begin{bmatrix} TEST \\ \hline $	This is used to adjust the the resolution.Short-circuit across termOpen across terminals	e offset/gain value and to set ninals 1 and 3 Test mode 1 and 3 Normal mode
(6)	Output hold/clear setting terminal	This sets the CH3 analog CPU is stopped. Open across terminals 2 output when the CPU is Short-circuit across term value is output when the	g output state when the PLC and 4: The offset value is stopped (clear) inals 2 and 4: The analog CPU is stopped (hold)
(7)	Analog input terminal(CH1, CH2) $\begin{bmatrix} V^{+} & & \\ I^{+} & & \\ C & & \\ I^{-} & \\ SLD & & \\ V^{+} & & \\ C & & \\ I^{+} & \\ C & & \\ SLD & & \\ SLD & & \\ \end{bmatrix}$	The CH1 and CH2 analo are input.	og values (voltage/current)
(8)	Analog output terminal(CH3) $\downarrow_{C} \xrightarrow{V+} \bigvee_{-} \bigotimes$ $\downarrow_{3} \xrightarrow{1+} \bigotimes$ \bigotimes	The CH3 analog values	(voltage/current) is output.
(9)	Analog ground	This is the ground termin	nal for the analog signal.
(10)	Frame ground terminal	This is the module's grou	und terminal.
(11)	Terminal block	The numbers in the draw	ing indicate the terminal No.

3.2 Setting the offset and gain

Use the following procedure to change the input/output conversion characteristics.



(1)



-(B)

YES

►(C)



Remark

The offset value and gain values are set as follows.

- (1) A/D conversion section
 - (a) The offset value is the analog input value (voltage or current) at which the digital output value is "0".
 - (b) The gain value is the analog input value (voltage or current) at which the digital output value is one of the following.
 - 1. 2000 (resolution 1/4000)
 - 2. 4000 (resolution 1/8000)
 - 3. 6000 (resolution 1/12000)
- (2) D/A conversion section
 - (a) The offset value is the analog value (voltage or current) output from the A1S63ADA when the digital value is "0".
 - (b) The gain value is the analog value (voltage or current) output from the A1S63ADA when the digital value is one of the following.
 - 1. 4000 (resolution 1/4000)
 - 2.8000 (resolution 1/8000)
 - 3. 12000 (resolution 1/12000)

4. HANDLING

4.1 Precautions for handling

- (1) As the body case and terminal block are made of resin, do not drop these or apply strong impacts.
- (2) Do not remove the module's PCB from the case. Failure to observe this could lead to faults.
- (3) Make sure that foreign matter such as wire scraps do not enter the module from the top while wiring. If any foreign matter enters, remove it.
- (4) Tighten the module tightening screws and terminal screws, etc., within the following range.

Screw position	Tightening torque range
Module tightening screw (M4 screw)	78 to 118N • cm
Terminal block terminal screw (M3.5 screw)	59 to 88N • cm
Terminal block installation screw (M4 screw)	78 to 118N • cm

5. WIRING

The precautions for wiring and examples of connecting the module are given in this section.

5.1 Precautions for wiring

One condition for creating a highly reliable system and using the A1S63ADA functions to the fullest is to carry out wiring that is not easily "affected by noise".

Precautions for wiring are given below.

- (1) Use separate cables for the alternating current and A1S63ADA analog input, and make sure that the alternating current side is not affected by surge or induction.
- (2) Do not wire near or with the main circuit wires, high-voltage wires or load wire other than from the PLC. If laid close together, the wires will be affected by noise, surge and induction.
- (3) Ground the shield wire or the shield of the shield cable at one point on the PLC side.

Note that depending on the state of noise from the external source, these should be grounded on the external side.

5.2 Example of module connection

The method for wiring the A1S63ADA is shown below.

- (1) CH1 and CH2
 - (a) For voltage input

Signal source 0 to ±10V



- *1: Use a 2-core twisted shield wire for the wire.
- *2: This indicates the A1S63ADA input resistance.
- *3: When inputting the current, always connect the (V+) and (I+) terminals.
- *4: If noise or ripple is generated in the external wire, connect an approx. 0.1 to 0.47μF25WV capacitor between terminal V and COM.
- *5: If there are high levels of noise, always ground. There may be cases where the power supply unit FG or main module FG should also be grounded.

If the grounding wire is changed (connected or disconnected) after setting the offset value and gain value, set the offset value and gain value again.

- (2) CH3
 - (a) For voltage output



(b) For current output



- *1: Use a 2-core twisted shield wire for the wire.
- *2: If noise or ripple is generated in the external wiring, connect a 0.1 to 0.47μF capacitor (approximate 25V or more withstand voltage) between the terminal V and COM.

IMPORTANT

The voltage and current output of the same channel cannot be used simultaneously.

The internal element will be damaged if used together, so always open the terminals that are not in use.

6. EXTERNAL DIMENSIONS DIAGRAM



Unit: mm(inch)

MEMO

MEMO

WARRANTY

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